FORM TO SPECIFY INPUT DATA FOR OCEAN-BOTTOM MODEL GTANH

This model represents the ocean bottom by a sequence of linear segments that are smoothly joined by hyperbolic functions:

$$g(r, \theta, \phi) = h - z(\theta)$$
, where

$$z(\theta) = z_{o} + \frac{c_{1}}{2} (\theta - \theta_{o}) - \sum_{i=1}^{n} \delta_{i} \left(\frac{c_{i+1} - c_{i}}{2}\right) \quad \ln \left\{ \frac{\cosh\left(\frac{\theta - \theta_{i}}{\delta_{i}}\right)}{\cosh\left(\frac{(\theta_{i} - \theta_{o})}{\delta_{i}}\right)} \right\} + \frac{c_{n+1}}{2} (\theta - \theta_{o})$$

$$\frac{dz}{d\theta} = c_{1} + \sum_{i=1}^{n} \left(\frac{c_{i+1} - c_{i}}{2}\right) \left\{-\tanh\left(\frac{\theta - \theta_{i}}{\delta_{i}}\right) + 1\right\}$$

$$c_{i} = (z_{i} - z_{i-1})/(\theta_{i} - \theta_{i-1})$$

h = r - r_e, where r_e is the Earth radius, and r is the radial coordinate of the ray point. $\theta_i = \pi/2 - \lambda_i$. Thus, δ_i is the half-thickness of a region centered at approximately θ_i , in which $dz/d\theta$ changes from c_i to c_{i+1}. Start by drawing a profile using linear segments, and θ_i and z_i from the corners. Then select δ_i to round the corners. The final profile will not go through (θ_i, z_i) . Specify--

the model check for GTANH = 3.0 (W300)

the input data-format code = (W301)

an input data-set identification number = (W302)

an 80-character description of the model with parameters:

and the profile values:

the number of points in the profile -2 = n = the profile: i λ_i z_i δ_i (rad,deg) (km,m) (rad,deg)

OTHER MODELS REQUIRED: Any bottom-perturbation model. Use NPBOTM if no perturbation is desired. FUNCTION ALCOSH.